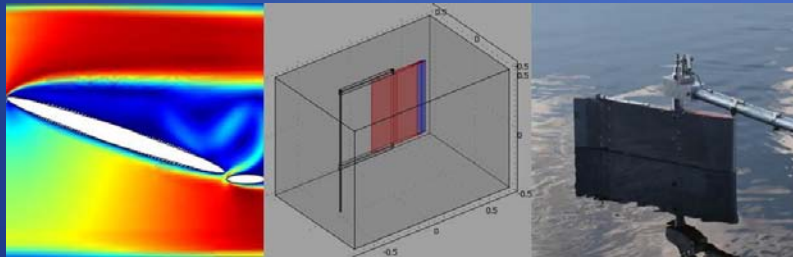


# Modeling an Oscillating Hydrofoil for Hydrokinetic Power Generation

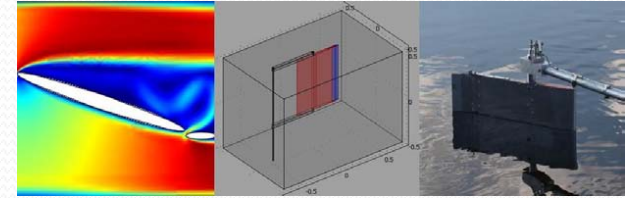
A Hydro-foil energy converter



**Rui Han**

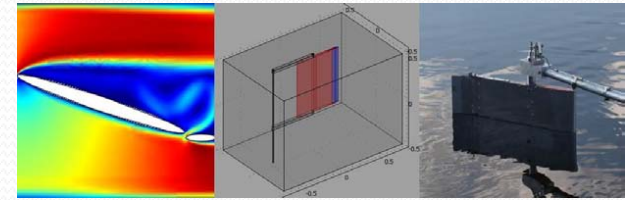
Student Research Assistant  
International Arctic Research Center  
Dept. of Electrical & Computer Engineering  
University of Alaska Fairbanks

# Contents

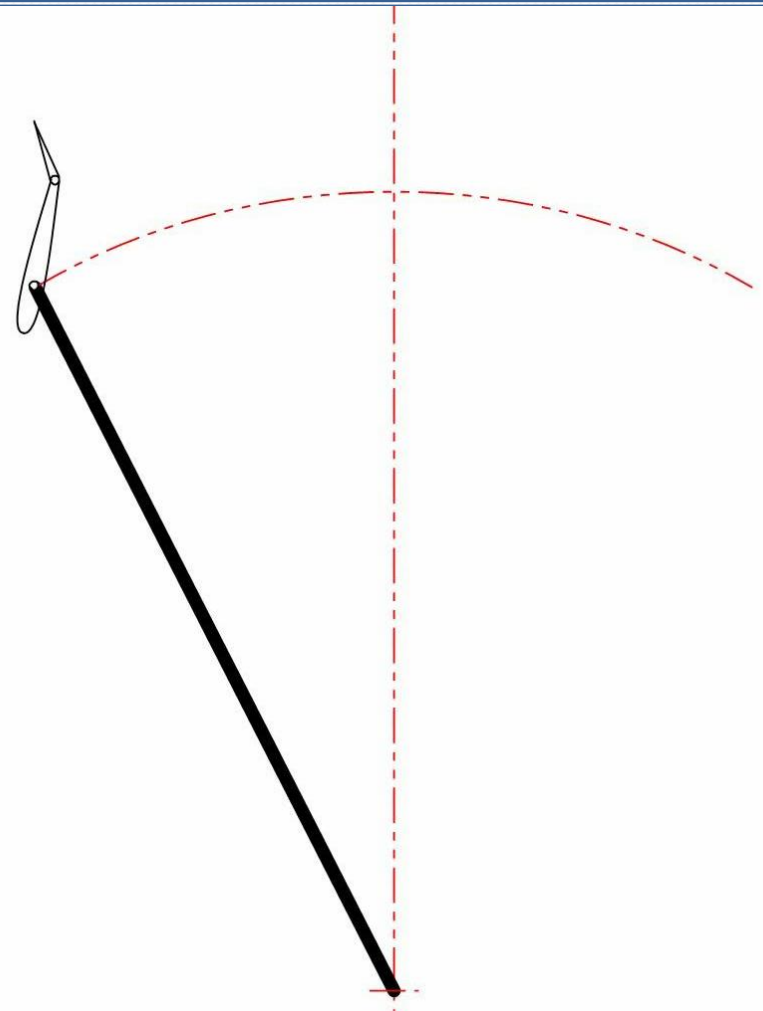
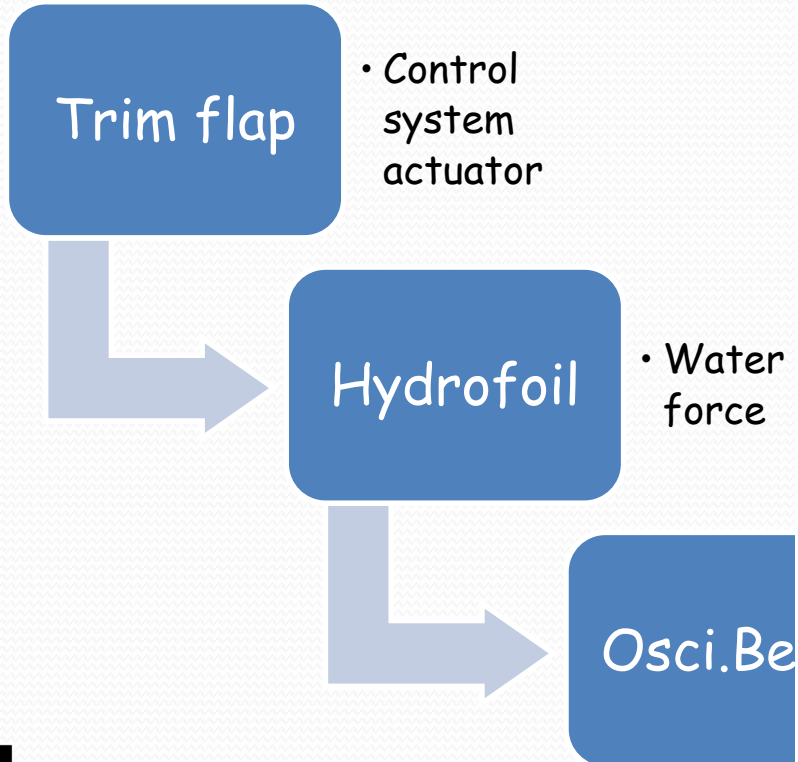


- Mechanism of the Controlled Hydrofoil
- Prototype
- Mathematical Model
- Foil motion
- 2D static model and results
- Challenges in 2D transient model
- Pros and cons for 3D model

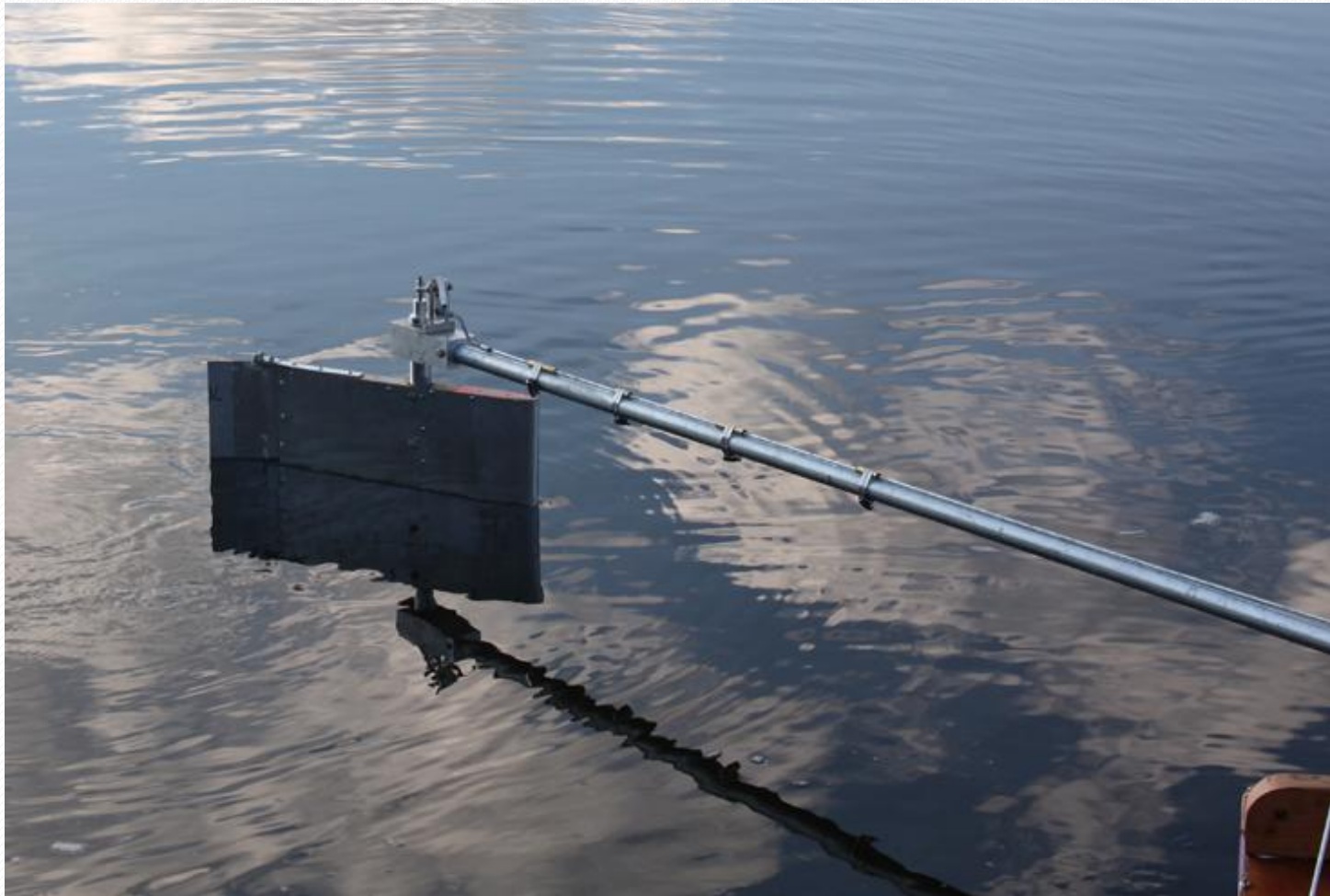
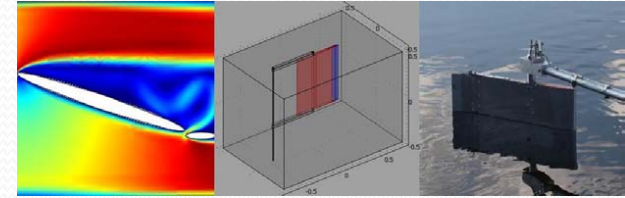
# Controlled Hydrofoil



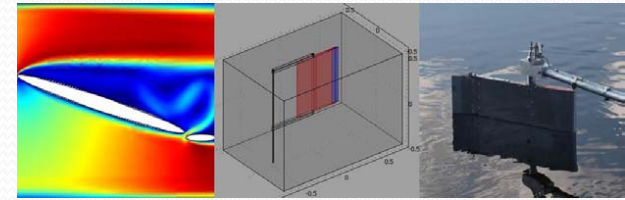
## • How it works?



# Hydrofoil Prototype



# Mathematical Model

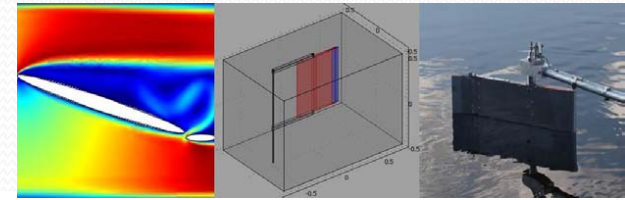


- Differential Equations for flowing water  
Navier-Stokes Equation:

$$\rho \frac{D\mathbf{V}}{Dt} = -\nabla p \mathbf{I} + \nabla \mu \left[ \nabla \mathbf{V} + (\nabla \mathbf{V})^T \right] + \rho \mathbf{g} \quad \text{In } \Omega \text{ for } t \in [0, T]$$

- $\rho$  – fluid density
- $p$  – pressure
- $\mu$  – fluid viscosity
- $\mathbf{V}$  – fluid velocity
- $\mathbf{g}$  – gravity of Earth

# Mathematical Model

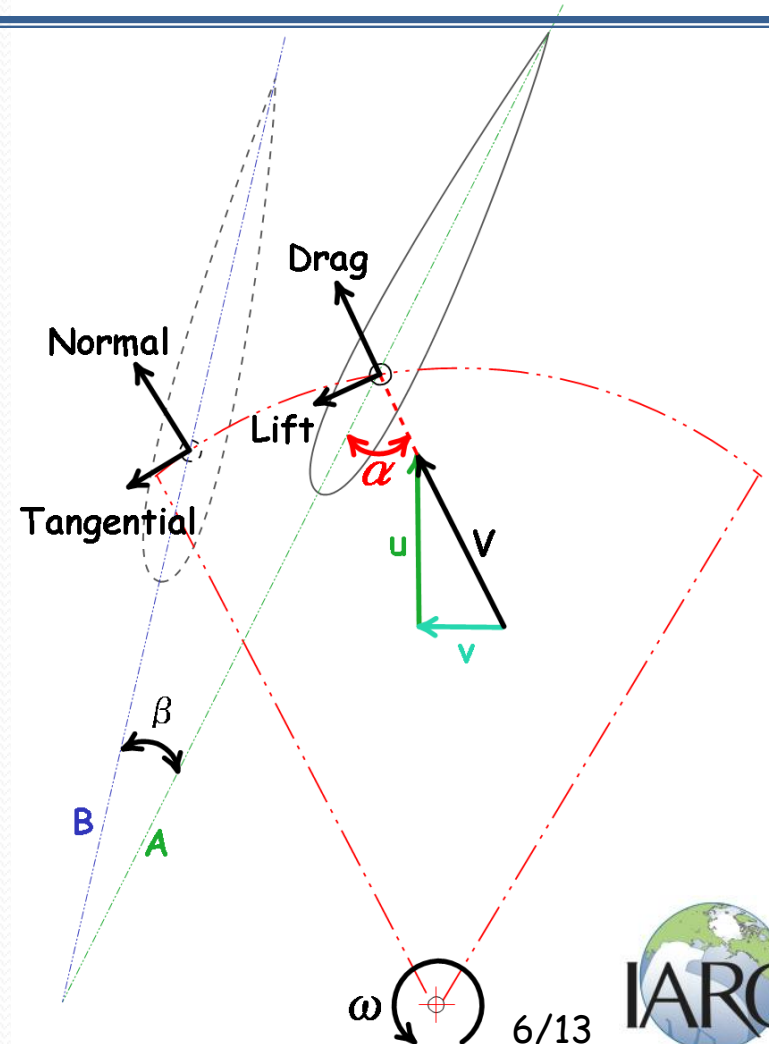


- Analysis of the foil motion
  - Harmonic transverse motion
  - Harmonic angular motion
  - With same period  $T$

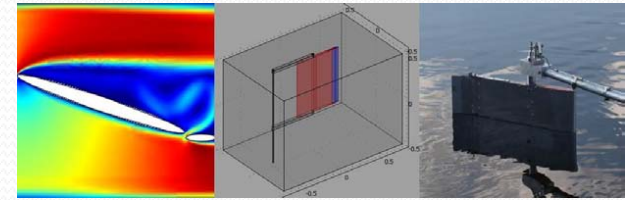
- Quantification of forces

$$L = \frac{1}{2} \rho \bar{V} S C_L \quad D = \frac{1}{2} \rho \bar{V} S C_D$$

$$T = L(\cos \gamma) + D(\sin \gamma)$$



# Foil Model in COMSOL



- **2D static Model**

- **Goal**

- Analyze the total static force acting on the foil
    - How different velocities affect the fluid force on the foil
    - Whether it generates enough force to drive PMG

- **Application mode**

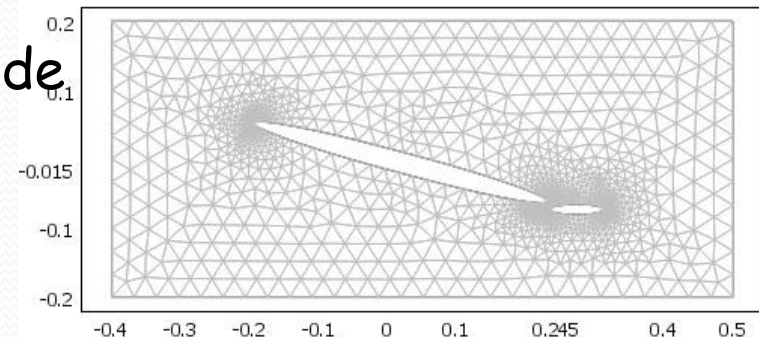
- Incompressible NS application mode

- **Boundary conditions**

- No Slip wall, inlet velocity, outlet

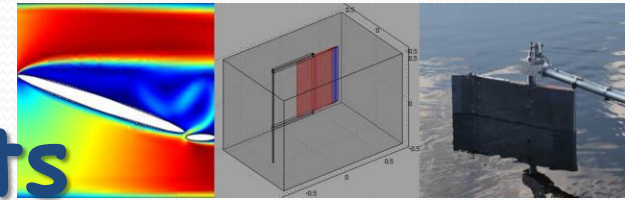
- **Solver**

- Parametric solver

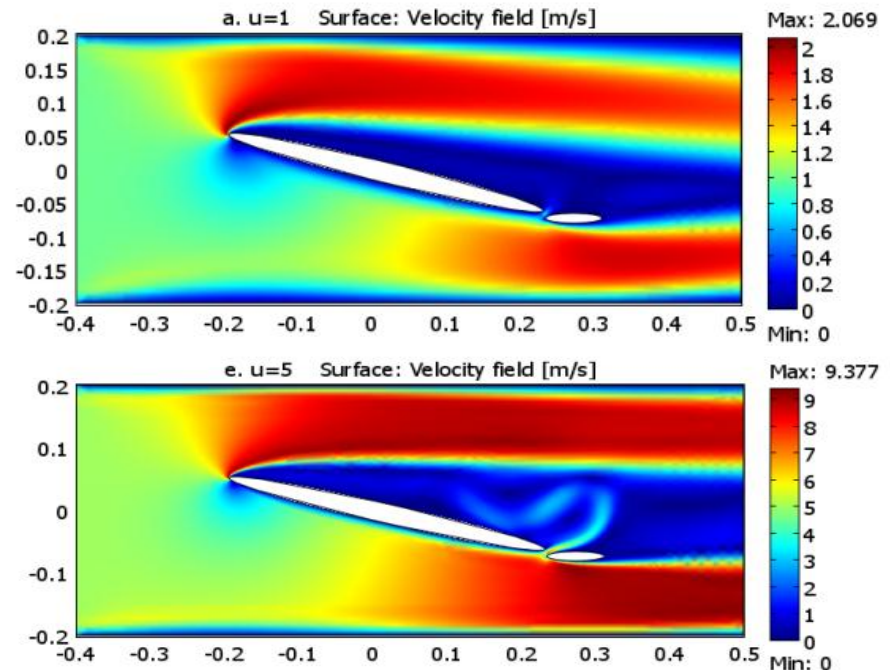
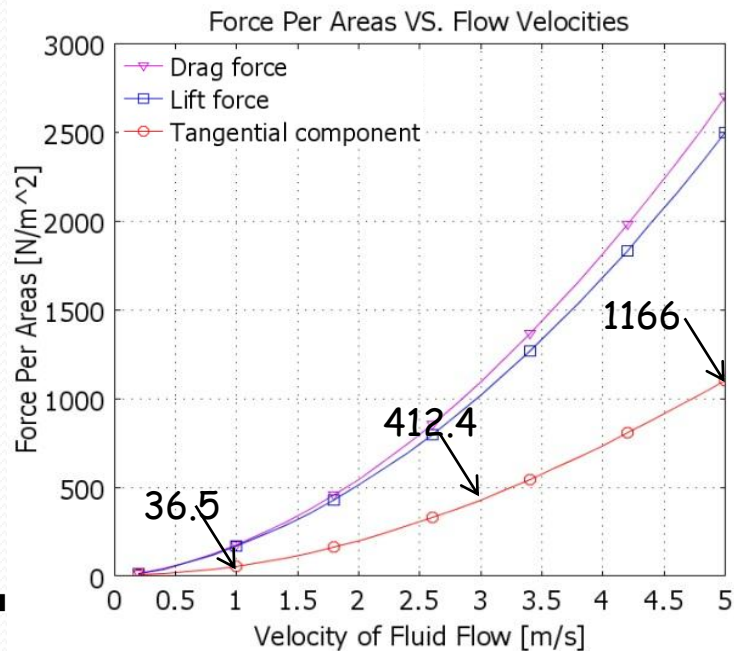


Mesh of 2D geometry model

# 2D Static Modeling Results

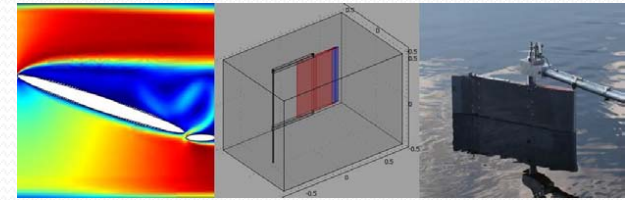


- Velocity distribution of the flow pass the foil
- Lift force, drag force, and the combination of the two to drive the rod





# Results Analysis



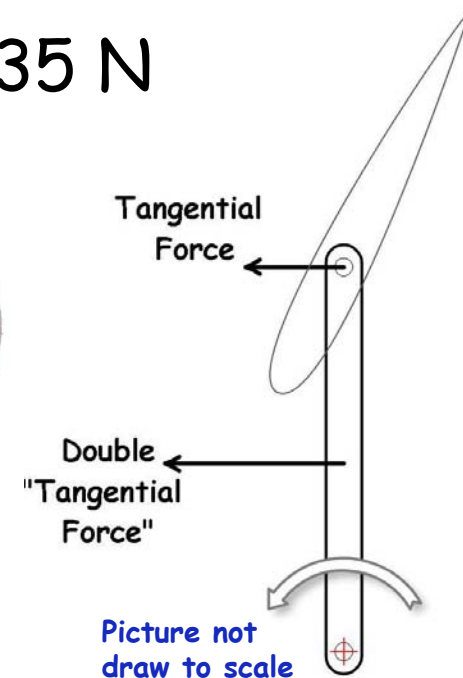
- 1 m/s  $\rightarrow$  36.5 N/m<sup>2</sup>
  - 3 m/s  $\rightarrow$  412.4 N/m<sup>2</sup>
  - 5 m/s  $\rightarrow$  1166 N/m<sup>2</sup>
- $S = 0.63\text{m}^2$
- 23 N
  - 260 N
  - 735 N

## Commercial PMG (eg. Ginlong)

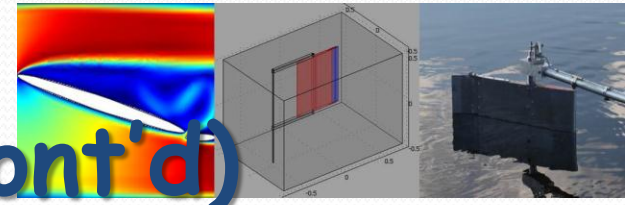
- 500 Watts require 14.8 N·m
- 30 Kilowatts require 3300 N·m

## Direct drive Power generator

Easier to drive



# Foil Model in COMSOL (cont'd)



- **2D transient Model (Unfinished)**

- **Goal**

- Analyze transient motion of the foil
- Estimate the output power in one oscillating period

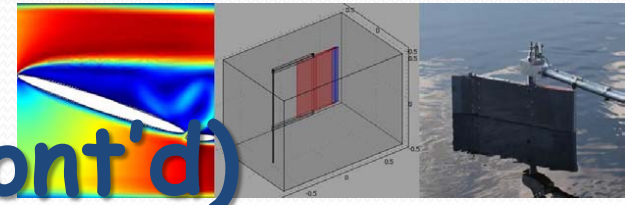
- **COMSOL application mode**

- Predefined Fluid Structure Interaction mode
- Rotating machinery mode

- **Challenges**

- How to model 3 relative moving frames
- Optimize solving time

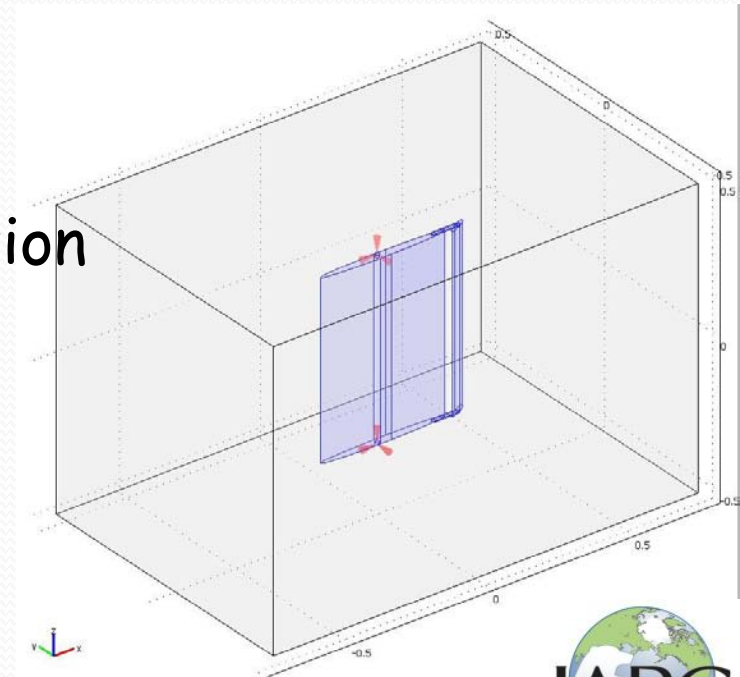
# Foil Model in COMSOL (cont'd)



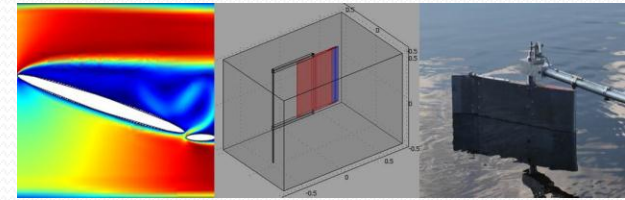
- 3D Model (optional)

- ✓ Better visualization of the model
- ✓ Provides more data

- ✗ Convergence problem
- ✗ Involving more boundary condition
- ✗ Structure mechanics coupling



# Future Challenges



- 3 relative free motions in 2D transient model
- Couple the Structure mechanics in 3D model
- Convergence problem in 3D model
- Integrate with Simulink control system

# Questions....

